

# GEMS OF TCS

## EASY AND HARD PROBLEMS

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Sasha Golovnev

August 24, 2022

# THEORETICAL COMPUTER SCIENCE

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$$P \implies Q$$

Mathematical  
logic

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Computability  
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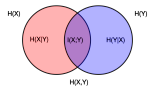
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$P = NP?$

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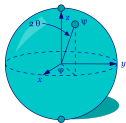
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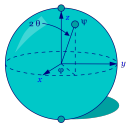
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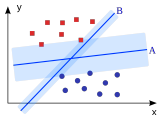
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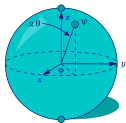
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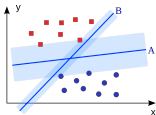
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Data Science

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- Theoretical/Mathematical viewpoint

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- email: `alexgolovnev+gems@gmail.com`

# COURSE BEGINS

- Running time of an algorithm



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- Complexity class **P**: Problems whose solution can be **found** efficiently
- Complexity class **NP**: Problems whose solution can be **verified** efficiently

The main open problem in Computer Science

Is **P** equal to **NP**?

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Millennium Prize Problem

Clay Mathematics Institute: \$1M prize for solving the problem

- If  $P=NP$ , then all  $NP$ -problems can be solved in polynomial time.

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- If  $P \neq NP$ , then there exist  $NP$ -problems that cannot be solved in polynomial time.



# NP-COMPLETE PROBLEMS

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# NP-COMPLETE PROBLEMS

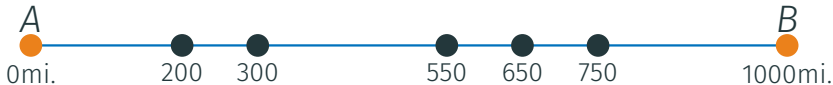
- The “hardest” problems in **NP**
- If any **NP**-complete problem can be solved in polynomial time, then all of **NP** can be solved in polynomial time
- If one **NP**-complete problem cannot be solved in polynomial time, then all **NP**-complete problems cannot be solved in polynomial time
- Later we'll show **NP**-complete problems exist!

# Car Fueling

# CAR FUELING

Distance with full tank 300 mi.

Minimize the number of stops at gas stations



Break <http://bit.ly/car-fueling>

## EXAMPLE

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Minimize the number of stops at gas stations





# CAR FUELING. SOLUTION

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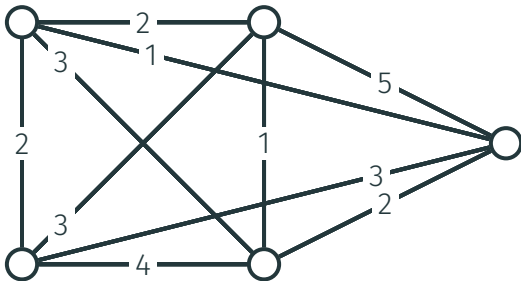
# CAR FUELING. SOLUTION

- “Greedy” algorithm
- Runs in **linear** time  $O(n)$ , where  $n$  is the size of the input (# of gas stations)
- Easy problem

# Traveling Salesman Problem (TSP)

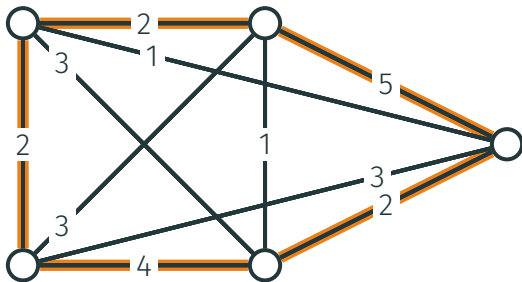
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Given a complete weighted graph, find a cycle (or a path) of minimum total weight (length) visiting each node exactly once



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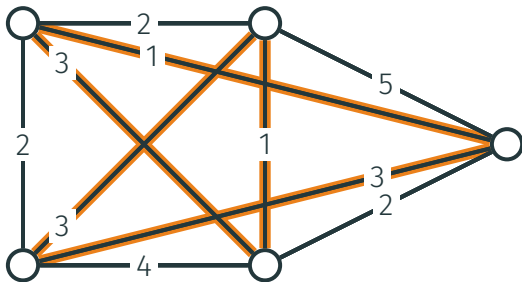
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length: 15

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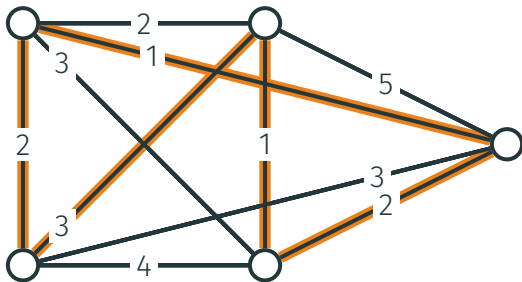
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length: 11

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- The best known algorithm runs in time  $2^n$

# DELIVERING GOODS

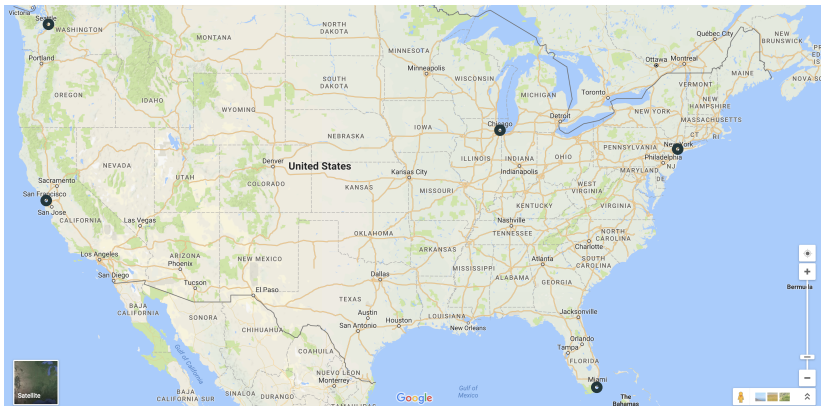


Need to visit several points. What is the optimal order of visiting them?

# TRAVELING



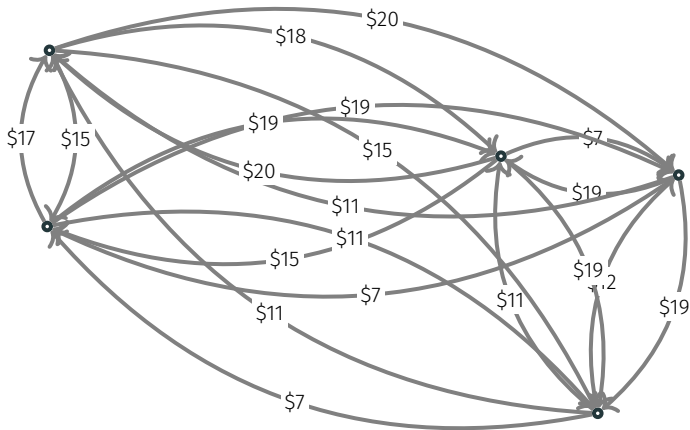
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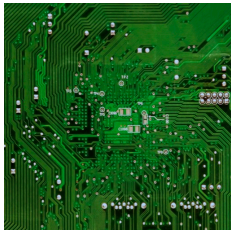


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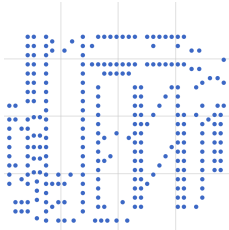
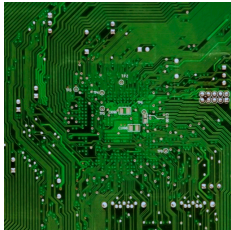


# DRILLING A CIRCUIT BOARD



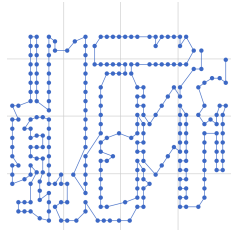
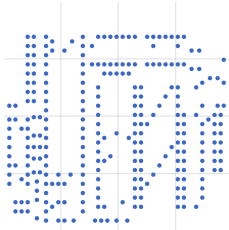
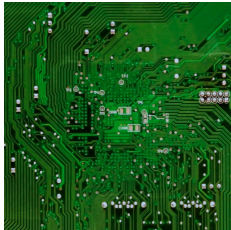
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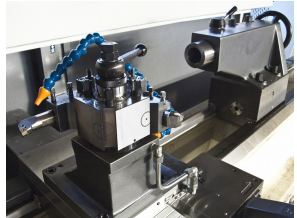
# DRILLING A CIRCUIT BOARD



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# PROCESSING COMPONENTS

There are  $n$  mechanical components to be processed on a complex machine. After processing the  $i$ -th component, it takes  $t_{ij}$  units of time to reconfigure the machine so that it is able to process the  $j$ -th component. What is the minimum processing cost?



# EUCLIDEAN TSP

- **Euclidean TSP:** instead of a complete graph, the input consists of  $n$  points  $p_1 = (x_1, y_1), \dots, p_n = (x_n, y_n)$  on the plane

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$$d(p_i, p_j) = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

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- Weights are symmetric:  $d(p_i, p_j) = d(p_j, p_i)$
- Weights satisfy the triangle inequality:  
$$d(p_i, p_j) \leq d(p_i, p_k) + d(p_k, p_j)$$



# BRUTE FORCE SEARCH

- Finding the best permutation is easy:  
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- Finding the best permutation is easy: simply iterate through all of them and select the best one
- But the number of permutations of  $n$  objects is  $n!$

## $n!$ : GROWTH RATE

---

$n$	$n!$
5	120
8	40320
10	3628800
13	6227020800
20	2432902008176640000
30	2652528598121910586363084800000000

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# Satisfiability Problem (SAT)

# SAT

$$(x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_3) \wedge (x_2 \vee \neg x_3)$$

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# APPLICATIONS OF SAT

- Software Engineering
- Chip testing
- Circuit design
- Automatic theorem provers
- Image analysis
- ...

# $k$ -SAT

$$\begin{aligned}\phi(x_1, \dots, x_n) = & (x_1 \vee \neg x_2 \vee \dots \vee x_k) \wedge \\ & \dots \wedge \\ & (x_2 \vee \neg x_3 \vee \dots \vee x_8)\end{aligned}$$



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$\phi$  is **satisfiable** if

$$\exists x \in \{0, 1\}^n : \phi(x) = 1.$$

Otherwise,  $\phi$  is **unsatisfiable**

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**$k$ -SAT** is SAT where clause length  $\leq k$

## $k$ -SAT. EXAMPLES

$$(x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_3) \wedge (x_2 \vee \neg x_3)$$

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$$(x_1) \wedge (\neg x_2) \wedge (x_3) \wedge (\neg x_1)$$

# QUEEN OF NP-COMPLETE PROBLEMS

- Cook-Levin Theorem [Coo71, Lev73]: SAT can model non-deterministic Turing machine:

SAT is NP-complete

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- Cook-Levin Theorem [Coo71, Lev73]: SAT can model non-deterministic Turing machine:  
SAT is NP-complete
- 3-SAT is NP-complete
- 2-SAT is in P

# COMPLEXITY OF SAT

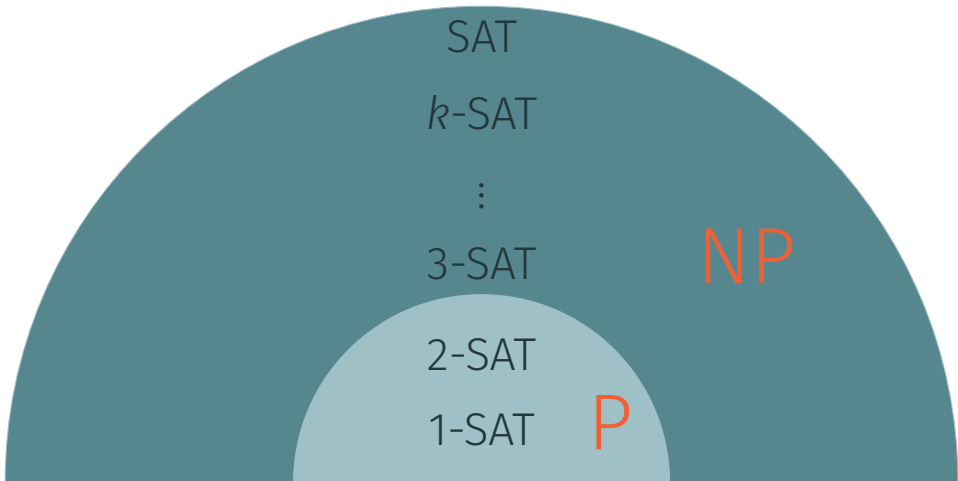
2-SAT

1-SAT

P



# COMPLEXITY OF SAT



The SAT game

<http://bit.ly/sat-game>